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(54) Title: CONTROL OF ROBOTIC MANIPULATION
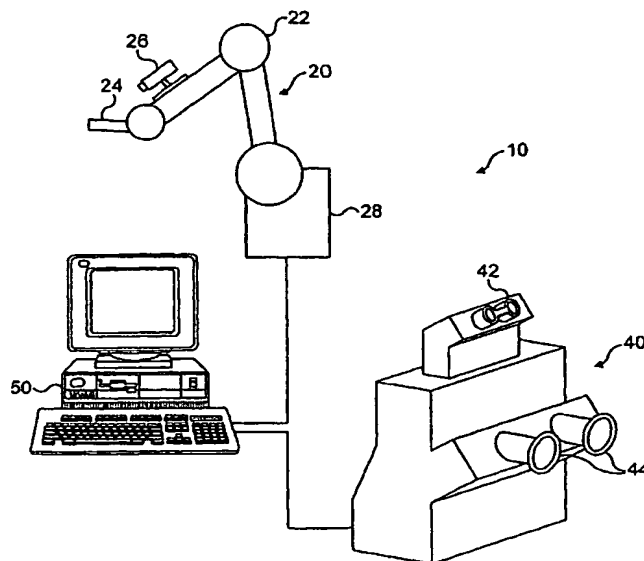
(57) Abstract: In a remote controlled robotic manipulator (20) a motion sensor (26) senses motion of a region of an object to be manipulated. A controller (50) locks motion of the robotic manipulator (26) relative to the region of the object and also selects the region of the object to be sensed. As a result the frame of reference of the manipulator is locked to the relevant region of the object to be manipulated improving ease of control and manipulation.